

A Hybrid Variance Reduction Method Based on Gaussian Process for Nuclear Reactor Analysis

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Introduction

- Deterministic method is fast but lack of flexibility and inaccurate
- Monte-Carlo (MC) method is universal and more physical reliable but time consuming
- Hybrid deterministic-MC methods have being recently getting more and more interest to researchers.
- Deterministic models solution (both forward and adjoint) is employed to bias source particles and assign appropriate importance map to MC models to accelerate MC simulation and reduce the variance.
- Some current developed hybrid approaches:
 - Variational variance reduction (Densmore & Larsen 2003)
 - Correction method (Becker et al. 2007)
 - **FW-CADIS (Wagner et al. 2007)**
 - Talley linear combination (Solomon et al. 2009)
 - Coarse mesh finite difference (Lee et al. 2009)

Challenges

- Multiple responses application
 - Importance for different responses are expected to be different
 - Adjoint calculation needs to perform individually for each response
 - Computational overheads become unacceptable with the increase of responses.
- Global and uniform variance reduction in the whole phase space

FW-CADIS Approach

- Adjoint deterministic model: $\mathbf{L}^*(\phi_i^*) = \frac{\partial R_i}{\partial \phi}$
- Adjoint solutions are employed to bias particle source distribution and weight window map
- Pseudo response - combine multiple responses with linear combination and the weight for each response is assigned as the reverse of the forward solutions

$$\xi = \sum_{i=1}^m R_i / \phi_i \quad \mathbf{L}^*(\phi^*) = \frac{\partial \xi}{\partial \phi}$$

Motivations of GP Approach

- Importance for different responses are expected to be correlated albeit they are different.
- Resulting responses uncertainties are expected to be correlated
 - Given m responses, let r denote number of independent correlations.
 - Bias MC particles towards r (*rather than m*) independent correlations
- Gaussian Process (GP) approach is developed on these ideas

Correlations?

- Given m random variables: $X_1, \dots, X_m$
- Correlations are described by:

$$\text{cov}(X_i, X_j) = E[(X_i - X_i^\mu)(X_j - X_j^\mu)] = C_{i,j}$$

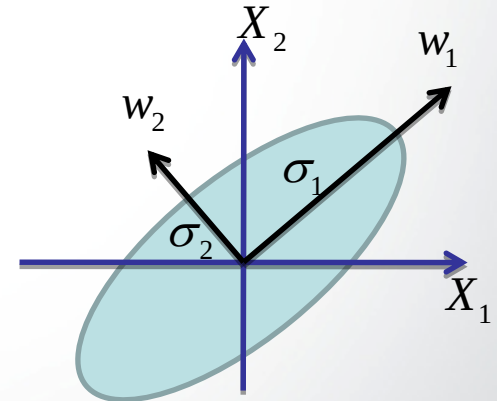
$$\mathbf{C} = \mathbf{W}\mathbf{\Sigma}^2\mathbf{W}^T \approx \mathbf{W}_r\mathbf{\Sigma}_r^2\mathbf{W}_r^T$$

$$\rightarrow \mathbf{W} = [w_1 \quad \dots \quad w_m] \in \mathbf{R}^{m \times m}$$

$$\rightarrow \mathbf{\Sigma} = \text{diag}\{\sigma_1, \dots, \sigma_m\} \in \mathbf{R}^{m \times m}$$

$$\rightarrow \mathbf{W}_r = [w_1 \quad \dots \quad w_r] \in \mathbf{R}^{m \times r}$$

$$\rightarrow \mathbf{\Sigma}_r = \text{diag}\{\sigma_1, \dots, \sigma_r\} \in \mathbf{R}^{r \times r}$$



Gaussian Process (GP) Approach

- Radiation transport may be treated as a Gaussian Process¹
- If responses correlations (covariance matrix) can be constructed and effective rank r can be estimated, one can reduce it to identify r uncorrelated pseudo responses
- r pseudo responses are formed in **GP** approach

$$\xi_j^{\text{GP}} = \sum_{i=1}^m w_{i,j} R_i, \quad j = 1, \dots, r$$

¹M. KENNEDY and A. O'HAGAN, "Bayesian calibration of computer model," *Journal of the Royal Statistical Society*, **63**, 3, 425–464 (2001).

GP Approach - Estimating Responses Covariance Matrix

Let $\bar{R} = [R_1 \ R_2 \ \dots \ R_m]^T \in \mathbf{R}^m$ represent a vector of the m responses of interest representing m random Gaussian processes. Denote $\{R_i^k\}_{i=1}^m$, $k = 1, 2, \dots, N$ as N realizations of these random processes. The covariance between the two responses R_i and R_j is given by:

$$\text{cov}(R_i, R_j) = \lim_{N \rightarrow \infty} \frac{1}{N-1} \sum_{k=1}^N (R_i^k - \hat{R}_i)(R_j^k - \hat{R}_j)$$

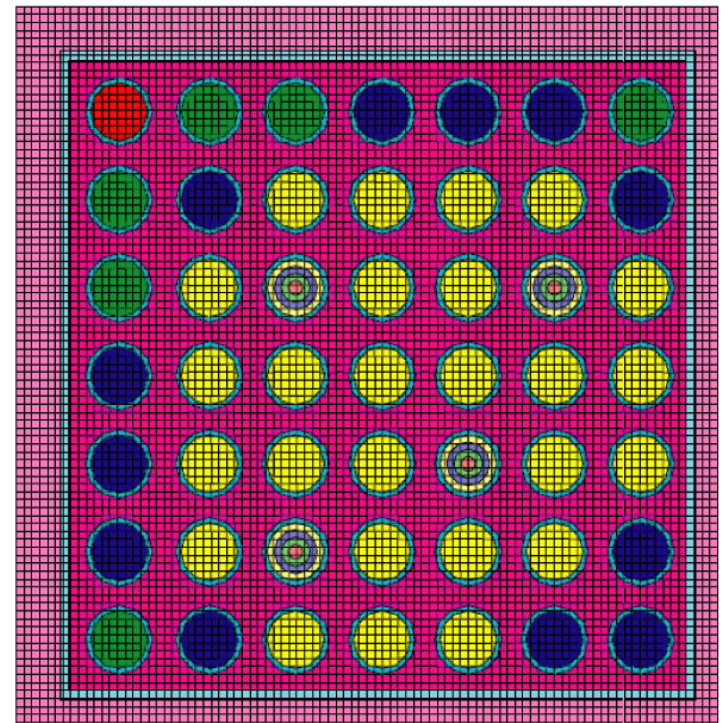
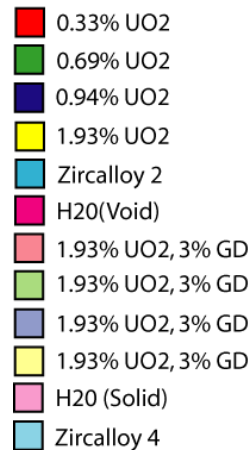
The covariance information between all pairs of m responses may also be represented by a symmetric covariance matrix $\mathbf{C} \in \mathbf{R}^{m \times m}$ such that: $C_{ij} = \text{cov}(R_i, R_j)$. The SVD form of this matrix is:

$$\mathbf{C} = \mathbf{W}\mathbf{\Sigma}^2\mathbf{W}^T = \sum_{i=1}^m \sigma_i^2 \bar{\mathbf{w}}_i \bar{\mathbf{w}}_i^T \approx \sum_{i=1}^r \sigma_i^2 \bar{\mathbf{w}}_i \bar{\mathbf{w}}_i^T = \mathbf{C}_r$$

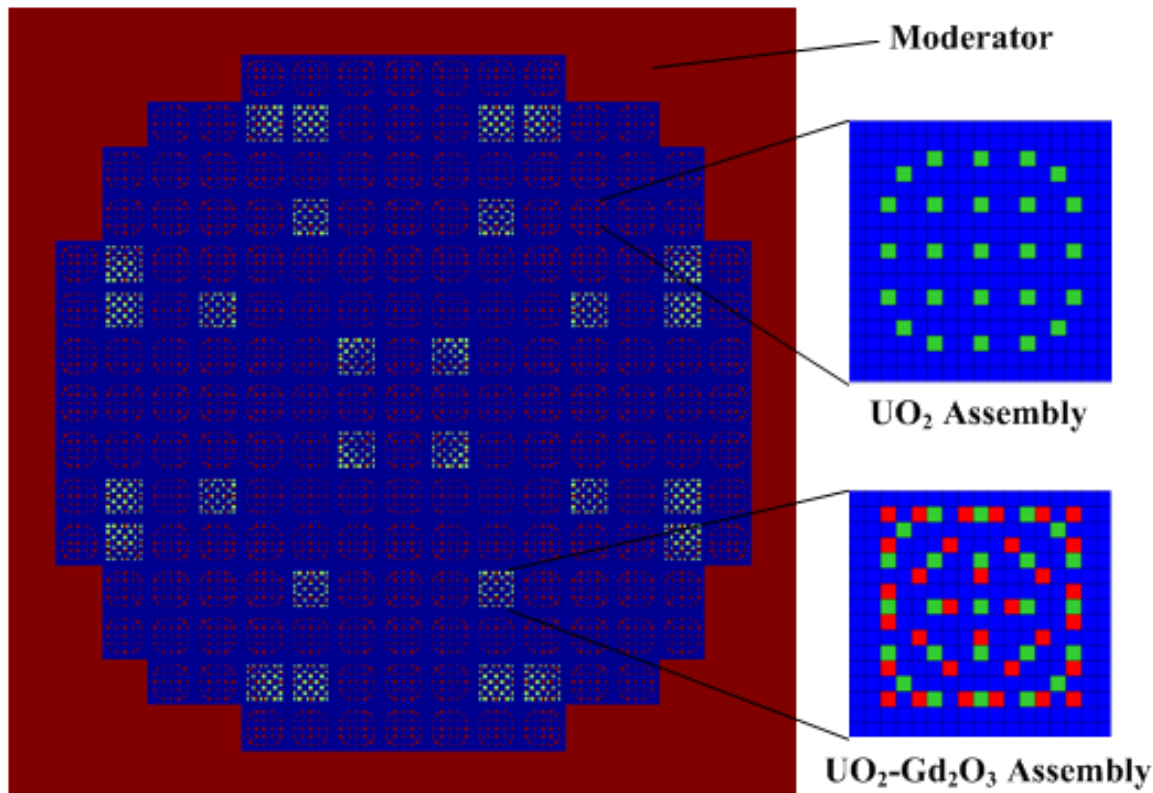
Numerical Applications

Case Study 1: BWR Assembly Model

- Code: *MAVRIC* sequences in *SCALE* package
- BWR Assembly, 7x7 array of fuel pins with various enrichments
- Fixed source subcritical system
- Total 27 neutron and 19 photon energy group library are applied

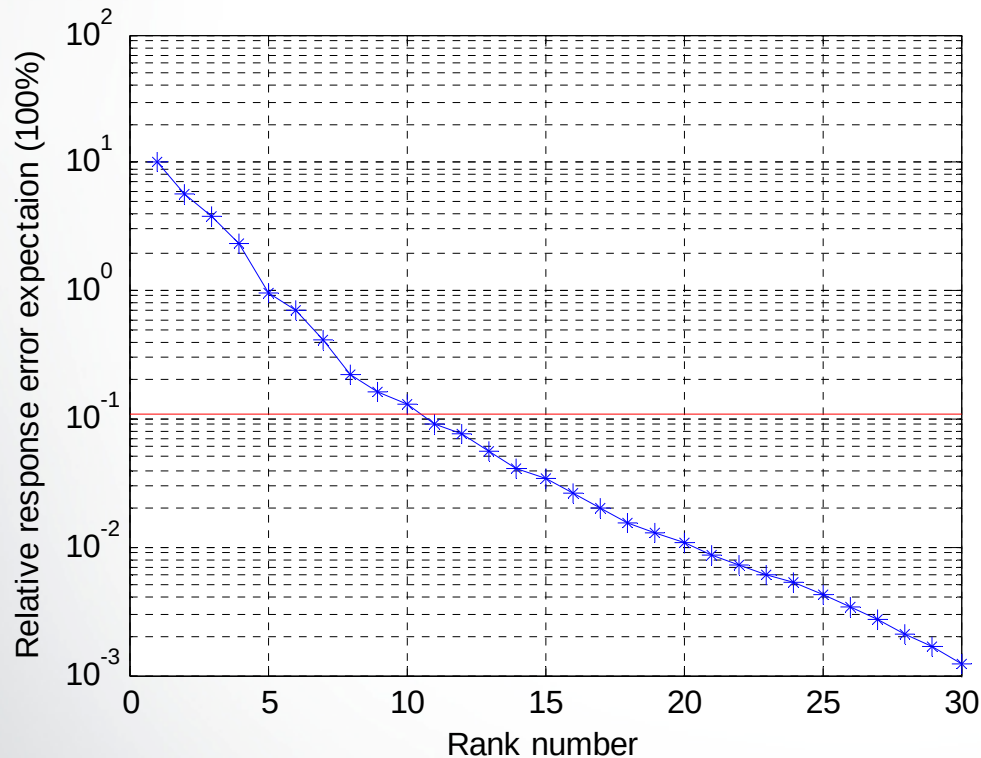


Case Study 2: PWR Core Model



- X-Y view of the core loading pattern with details assembly described on the side
- Total 193 fuel assemblies (blue region) laid out a 17x17 grid scheme and surrounded by light water (red region)
- Two types of fuel assemblies are designed: UO_2 fuel assembly and a $\text{UO}_2\text{-Gd}_2\text{O}_3$ fuel assembly.

Estimate of the Effective Rank for Covariance Matrix



SVD of Covariance Matrix:

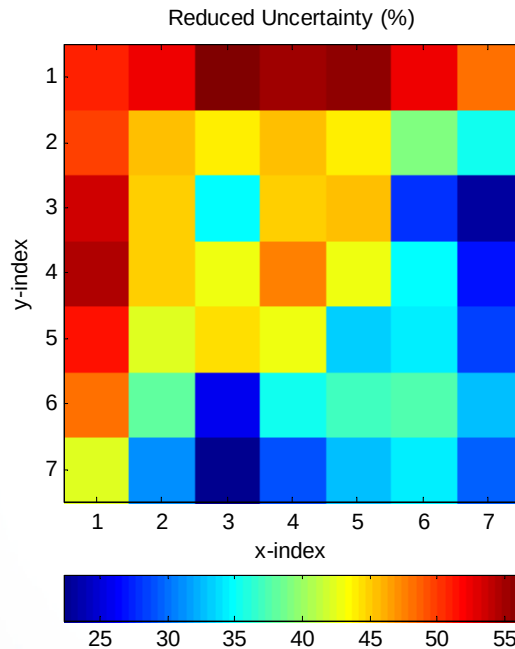
$$\mathbf{C} = \mathbf{W}\mathbf{\Sigma}^2\mathbf{W}^T = \sum_{i=1}^m \sigma_i^2 \bar{\mathbf{w}}_i \bar{\mathbf{w}}_i^T$$

Truncated SVD Approximation:

$$\mathbf{C}_r = \sum_{i=1}^r \sigma_i^2 \bar{\mathbf{w}}_i \bar{\mathbf{w}}_i^T$$

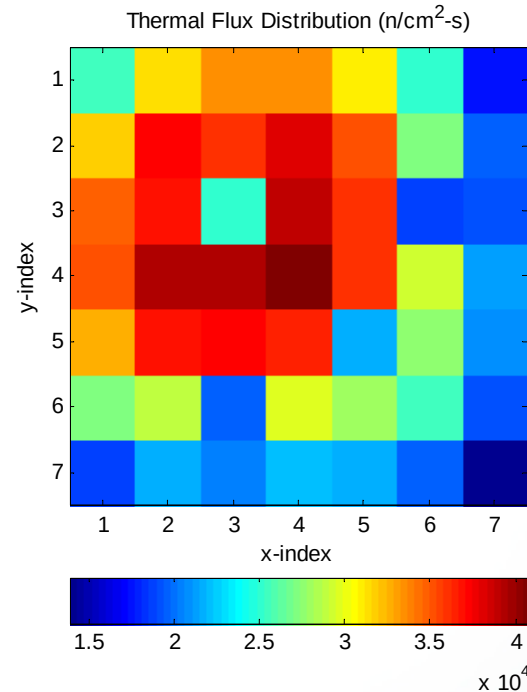
Search Criterion: $\|\mathbf{C} - \mathbf{C}_r\| < \delta$

Relative Uncertainty Comparison for Thermal Flux (GP vs. FW-CADIS, Assembly Model)



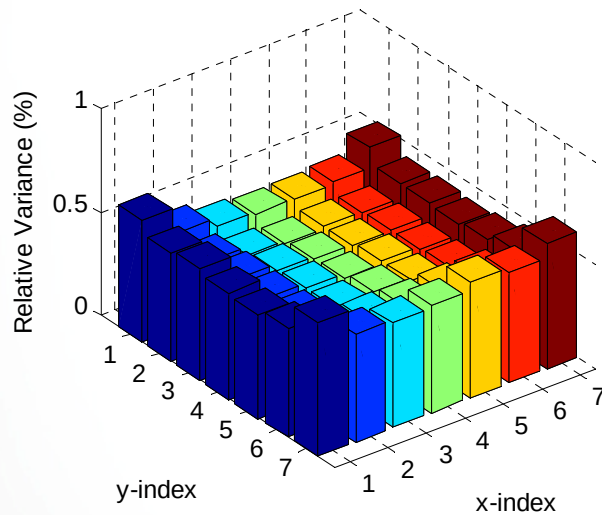
a. Standard Deviation Reduction

$$\text{Metric: } \varepsilon_i = \frac{\sigma_i^{\text{FW-CADIS}} - \sigma_i^{\text{GP}}}{\sigma_i^{\text{FW-CADIS}}} \times 100\%$$

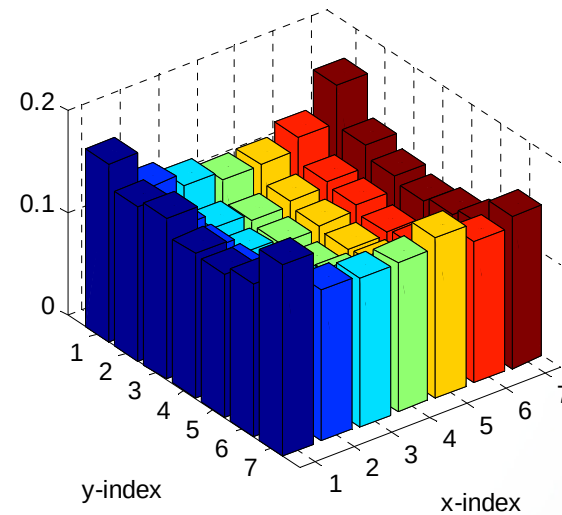


b. Mean Thermal Flux Distribution

Global Uniformity of Variance (GP vs. FW-CADIS, Assembly Model)

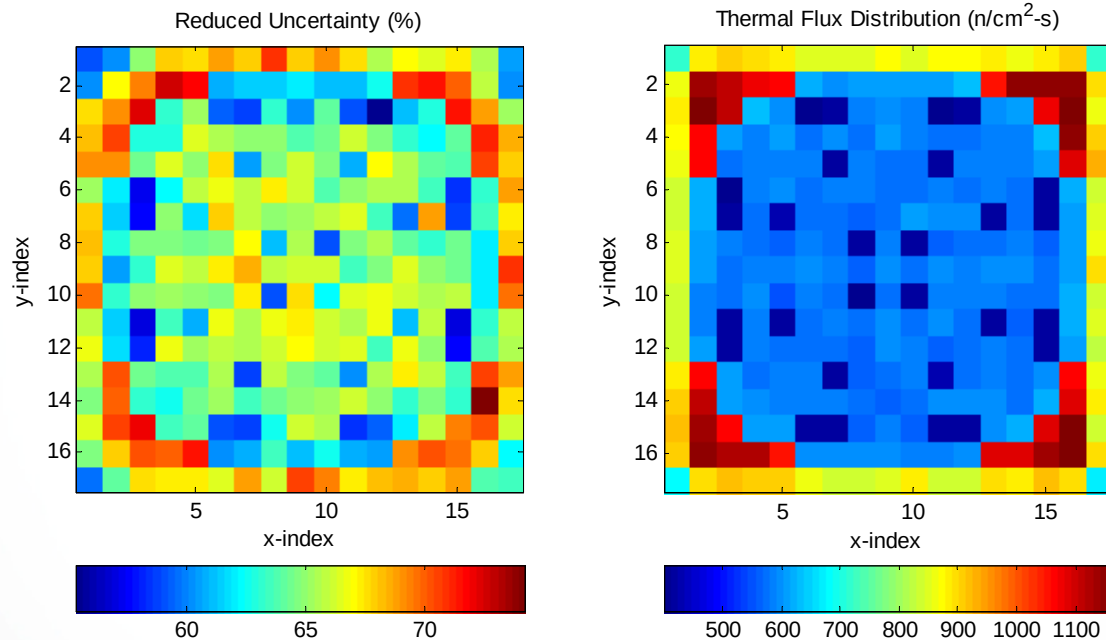


a. FW-CADIS Approach



b. GP Approach

Relative Uncertainty Comparison for Thermal Flux (GP vs. FW-CADIS, Core Model)

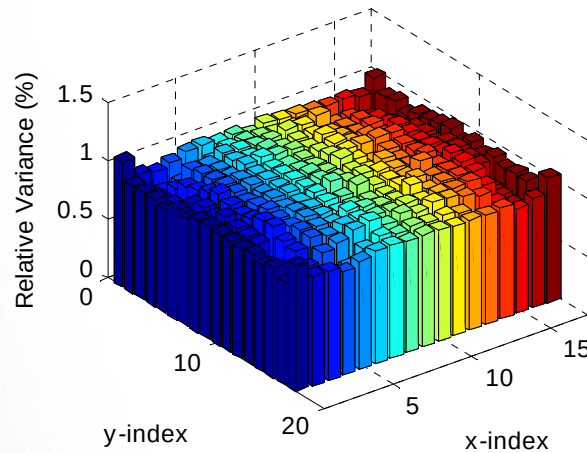


a. Standard Deviation Reduction

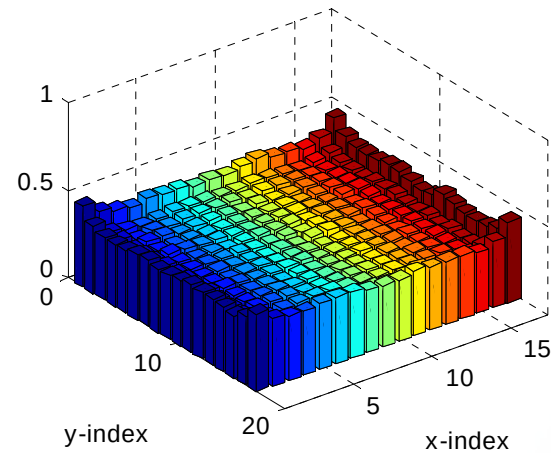
b. Mean Thermal Flux Distribution

$$\text{Metric: } \varepsilon_i = \frac{\sigma_i^{\text{FW-CADIS}} - \sigma_i^{\text{GP}}}{\sigma_i^{\text{FW-CADIS}}} \times 100\%$$

Global Uniformity of Variance (GP vs. FW-CADIS, Core Model)



a. FW-CADIS Approach



b. GP Approach

Conclusions

- Number of independent correlations are much smaller than number of responses, when responses are required everywhere in phase space
- GP assumption provides one way to take advantage of responses uncertainties correlations and the deterministic models can be employed to identify correlations
- Simple numerical experiments show that GP approach successfully gain better convergence in MC simulation comparing to FW-CADIS approach
- This idea could be extended to other hybrid deterministic-MC techniques
- A hybrid between GP and FW-CADIS methodology is suggested to reach their combined benefits in the future